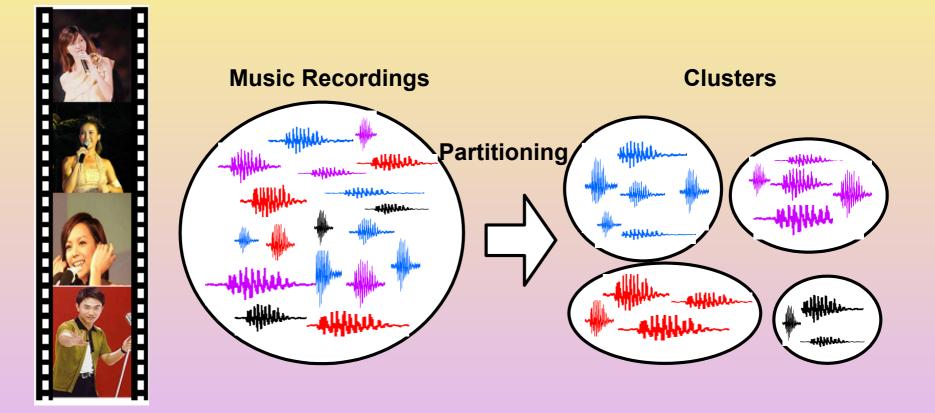
Blind Clustering of Popular Music Recordings Based on Singer Voice Characteristics

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## **The Task**

#### To cluster music recordings by singer



# **Applications**

#### Music data indexing

 Organizing unlabeled or insufficiently well labeled music collections such as live concert recordings and bootlegs.

#### Karaoke services

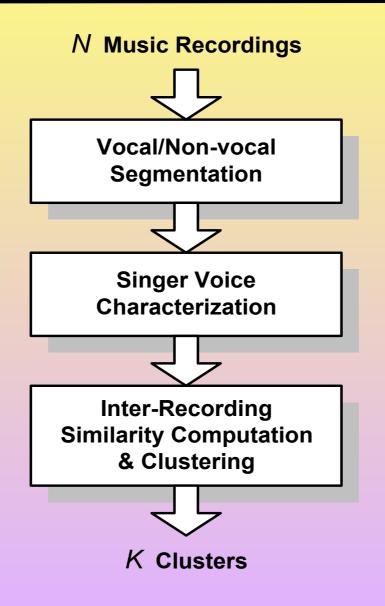
- Efficiently organizing the customers' recordings.
- Personalization

#### Music recommendation systems

- Suggesting music by singers with similar voices.

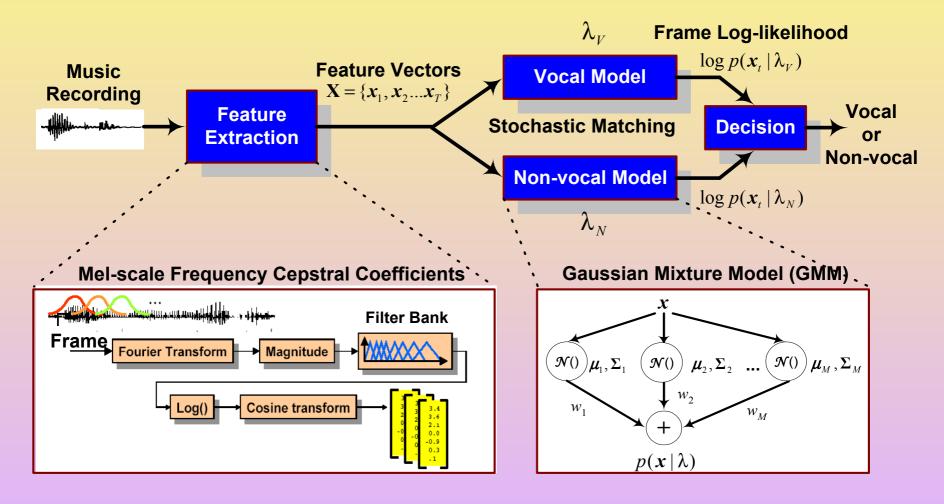
- Singer's voices tend to be arbitrarily altered from time to time
- The vast majority of popular music contains background accompaniment during most or all vocal passages

### **Method Overview**

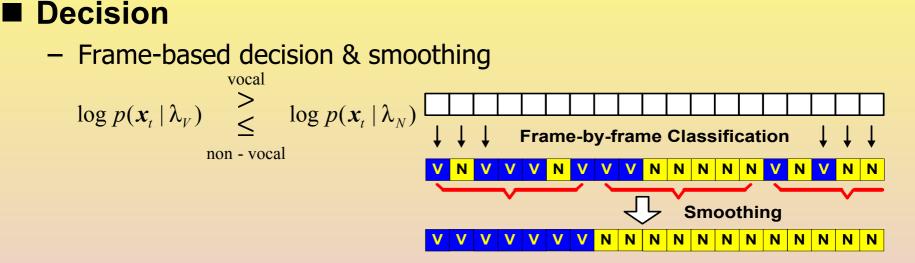


# **Vocal/Non-vocal Segmentation (I)**

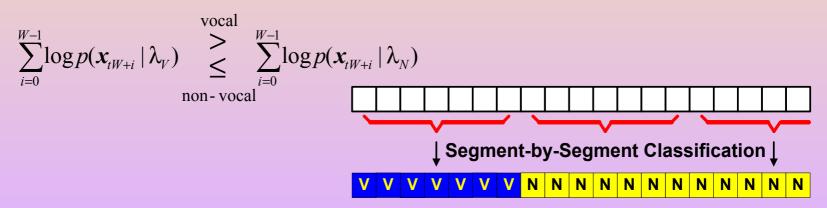
#### Block diagram



# **Vocal/Non-vocal Segmentation (II)**

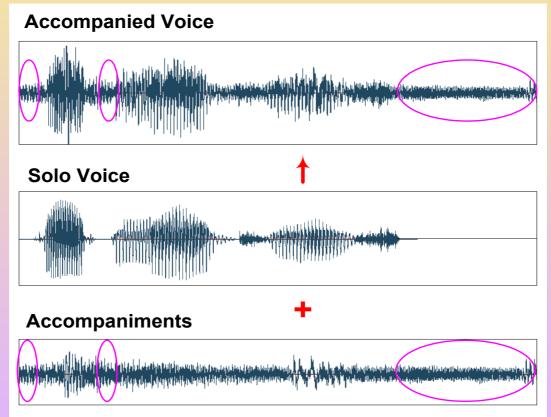


- Fixed-length-segment-based decision

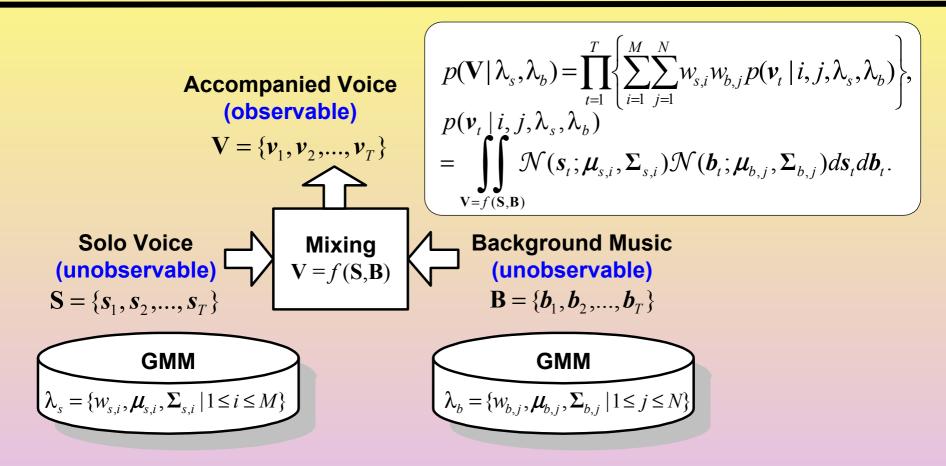


# **Cues For Singer Voice Characterization**

- Substantial similarities exist between the instrumental regions and the accompaniment of the vocal signal
- Solo voice can be modeled via suppressing the background music estimated from the instrumental regions

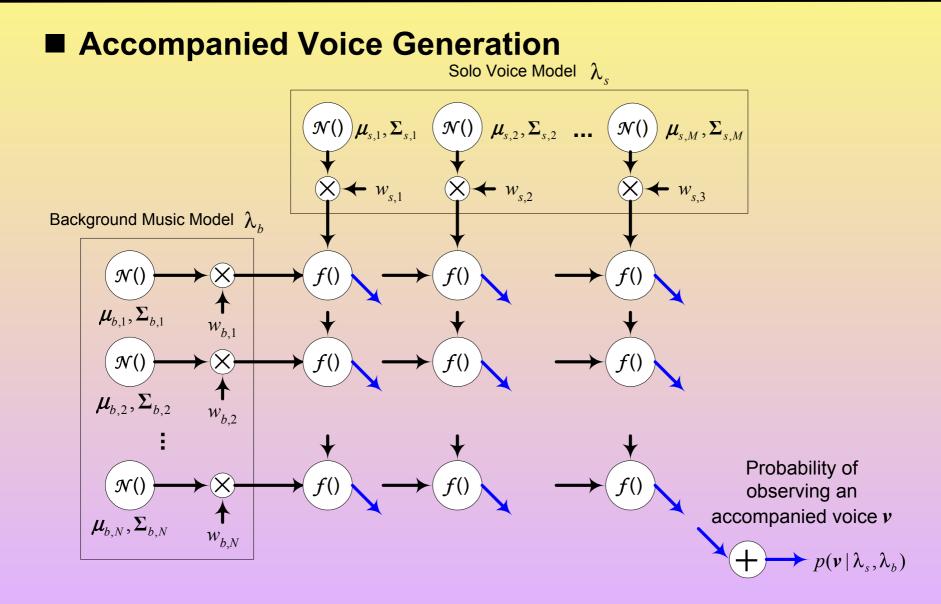


### Solo Voice Modeling (I)



-  $\lambda_b$  can be approximately estimated using the instrumental regions - Our aim is to find an optimal solo voice model  $\lambda_s$  such that  $\lambda_s^* = \underset{\lambda_s}{\operatorname{arg\,max}} p(\mathbf{V} | \lambda_s, \lambda_b).$ 

### **Solo Voice Modeling (II)**



#### Parameter estimation via Expectation-Maximization

- Defining an auxiliary function

$$Q(\lambda_s, \hat{\lambda}_s) = \sum_{t=1}^T \sum_{i=1}^I \sum_{j=1}^J p(i, j | \mathbf{v}_t, \lambda_s, \lambda_b) \log p(i, j, \mathbf{v}_t | \hat{\lambda}_s, \lambda_b),$$

where  $p(i, j, \mathbf{v}_t | \hat{\lambda}_s, \lambda_b) = w_{s,i} w_{b,j} p(\mathbf{v}_t | i, j, \hat{\lambda}_s, \lambda_b),$ 

$$p(i, j | \mathbf{v}_t, \lambda_s, \lambda_b) = \frac{w_{s,i} w_{b,j} p(\mathbf{v}_t | i, j, \lambda_s, \lambda_b)}{\sum_{m=1}^{I} \sum_{n=1}^{J} w_{s,m} w_{b,n} p(\mathbf{v}_t | m, n, \lambda_s, \lambda_b)}$$

- Letting  $\nabla Q(\lambda_s, \hat{\lambda}_s) = 0$  for each parameter to be re-estimated, we have  $\hat{w}_{s,i} = \frac{1}{T} \sum_{t=1}^{T} \sum_{j=1}^{J} p(i, j | \mathbf{v}_t, \lambda_s, \lambda_b),$ 

$$\hat{\boldsymbol{\mu}}_{s,i} = \frac{\sum_{t=1}^{T} \sum_{j=1}^{N} p(i, j \mid \boldsymbol{v}_t, \boldsymbol{\lambda}_s, \boldsymbol{\lambda}_b) \cdot E\{\boldsymbol{s}_t \mid \boldsymbol{v}_t, i, j, \boldsymbol{\lambda}_s, \boldsymbol{\lambda}_b\}}{\sum_{t=1}^{T} \sum_{j=1}^{N} p(i, j \mid \boldsymbol{v}_t, \boldsymbol{\lambda}_s, \boldsymbol{\lambda}_b)},$$

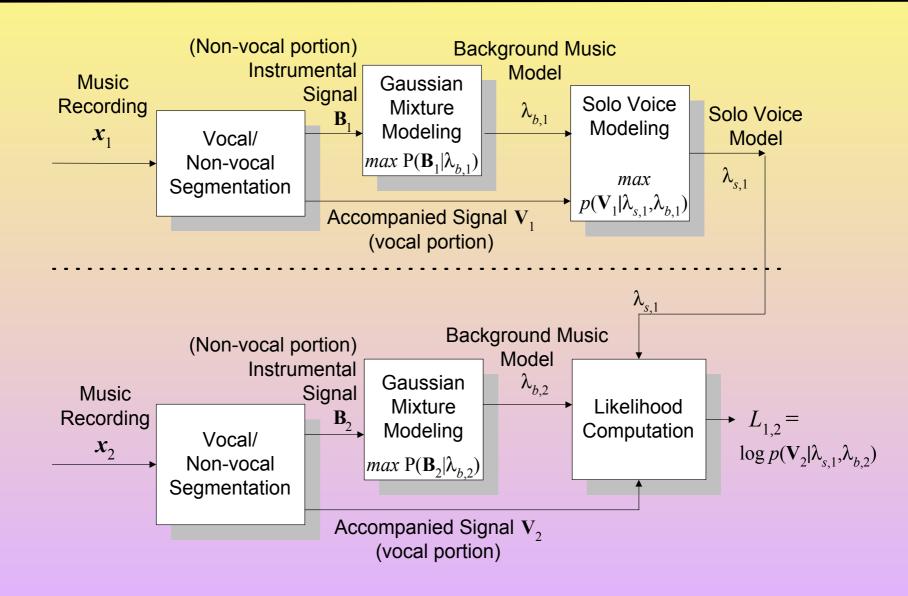
$$\hat{\boldsymbol{\Sigma}}_{s,i} = \frac{\sum_{t=1}^{T} \sum_{j=1}^{J} p(i, j \mid \boldsymbol{v}_{t}, \lambda_{s}, \lambda_{b}) \cdot E\{\boldsymbol{s}_{t} \boldsymbol{s}_{t}' \mid \boldsymbol{v}_{t}, i, j, \lambda_{s}, \lambda_{b}\}}{\sum_{t=1}^{T} \sum_{j=1}^{J} p(i, j \mid \boldsymbol{v}_{t}, \lambda_{s}, \lambda_{b})} - \boldsymbol{\mu}_{s,i} \boldsymbol{\mu}_{s,i}',$$

### **Solo Voice Modeling (IV)**

#### Re-estimation formulas for cepstral features

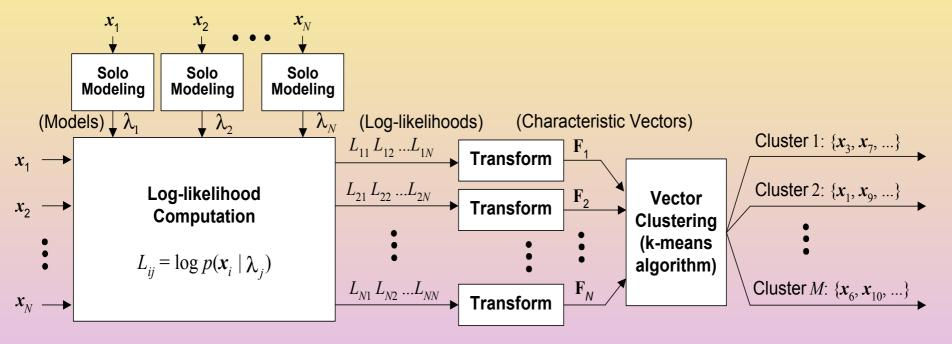
- Suppose V is a cepstral feature, and S and B are additive in the time domain, then  $v_t = \log[\exp(s_t) + \exp(b_t)]$ . We approximate  $v_t \approx \max(s_t, b_t)$ .
- It can be shown that  $p(v_t | i, j, \lambda_s, \lambda_b) = \mathcal{N}(v_t; \mu_{s,i}, \sigma_{s,i}^2) \Phi(\frac{v_t - \mu_{b,j}}{\sigma_{b,i}}) + \mathcal{N}(v_t; \mu_{b,j}, \sigma_{b,j}^2) \Phi(\frac{v_t - \mu_{s,i}}{\sigma_{s,i}}), \quad \Phi(\tau) = \int_{-\infty}^{\tau} \frac{1}{\sqrt{2\pi}} e^{-w^2/2} dw.$  $E\{s_t \mid v_t, i, j, \lambda_s, \lambda_b\} = p(s_t = v_t \mid i, j, \lambda_s, \lambda_b) \cdot v_t + (1 - p(s_t = v_t \mid i, j, \lambda_s, \lambda_b)) \cdot E\{s_t \mid s_t < v_t, i, j, \lambda_s, \lambda_b\},$  $E\left\{s_{t}^{2} \mid v_{t}, i, j, \lambda_{s}, \lambda_{b}\right\} = p(s_{t} = v_{t} \mid i, j, \lambda_{s}, \lambda_{b}) \cdot v_{t}^{2} + \left(1 - p(s_{t} = v_{t} \mid i, j, \lambda_{s}, \lambda_{b})\right) \cdot E\left\{s_{t}^{2} \mid s_{t} < v_{t}, i, j, \lambda_{s}, \lambda_{b}\right\}$  $\mathcal{N}(v_t; \boldsymbol{\mu}_{s,i}, \boldsymbol{\sigma}_{s,i}^2) \Phi(\frac{v_t - \boldsymbol{\mu}_{b,j}}{\boldsymbol{\sigma}_{b,j}}) = \frac{\mathcal{N}(v_t; \boldsymbol{\mu}_{s,i}, \boldsymbol{\sigma}_{s,i}^2) \Phi(\frac{v_t - \boldsymbol{\mu}_{b,j}}{\boldsymbol{\sigma}_{b,j}})}{\mathcal{N}(v_t; \boldsymbol{\mu}_{s,i}, \boldsymbol{\sigma}_{s,i}^2) \Phi(\frac{v_t - \boldsymbol{\mu}_{b,j}}{\boldsymbol{\sigma}_{b,j}}) + \mathcal{N}(v_t; \boldsymbol{\mu}_{b,j}, \boldsymbol{\sigma}_{b,j}^2) \Phi(\frac{v_t - \boldsymbol{\mu}_{s,i}}{\boldsymbol{\sigma}_{s,i}})},$  $E\{s_{t} | s_{t} < v_{t}, i, j, \lambda_{s}, \lambda_{b}\} = \mu_{s,i} - \sigma_{s,i} \frac{\mathcal{N}(v_{t}; \mu_{s,i}, \sigma_{s,i}^{2})}{\Phi(\frac{v_{t} - \mu_{s,i}}{\sigma_{s,i}})}.$   $E\{s_{t}^{2} | s_{t} < v_{t}, i, j, \lambda_{s}, \lambda_{b}\} = \mu_{s,i}^{2} + \sigma_{s,i}^{2} - (\mu_{s,i} + v_{t})\sigma_{s,i} \frac{\mathcal{N}(v_{t}; \mu_{s,i}, \sigma_{s,i}^{2})}{\Phi(\frac{v_{t} - \mu_{s,i}}{\sigma_{s,i}})}.$

# **Inter-recording Likelihood Computation**

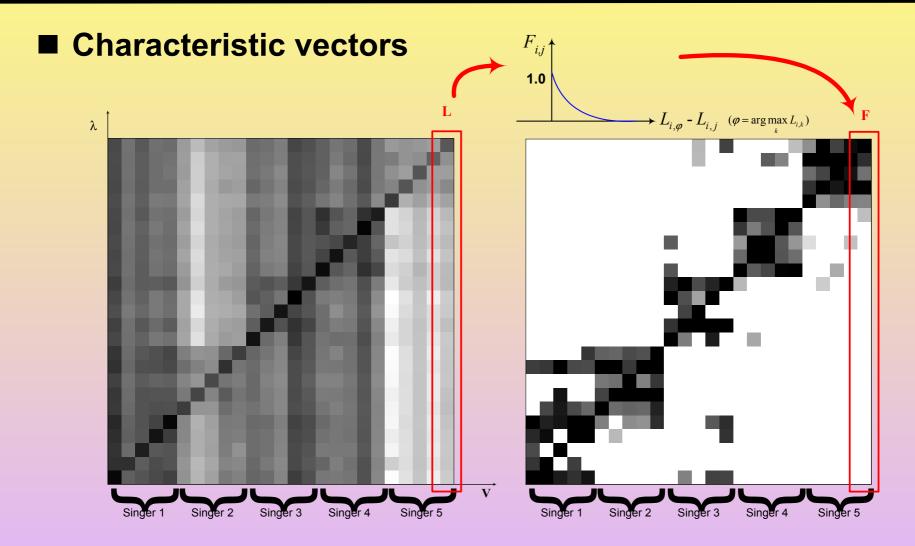


## **Singer-based Clustering (I)**

#### (Feature Vectors of Music Recordings)



### **Singer-based Clustering (II)**



- Converting into a problem of conventional vector clustering.

# **Determining The Number Of Clusters**

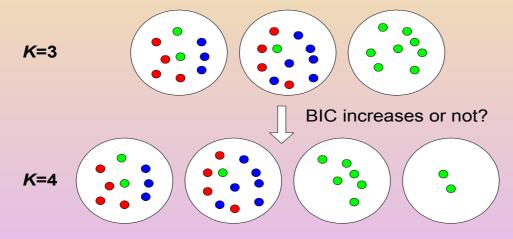
### Bayesian Information Criterion (BIC)

- Choosing one among a set of candidate models  $\{\Lambda_1, \Lambda_2, ..., \Lambda_K\}$  can best represent a given data set  $\mathcal{D}$ 

BIC( $\Lambda_i$ ) = log  $p(\mathcal{D} | \Lambda_i) - \frac{1}{2} \gamma d_i \log |\mathcal{D}|$ ,  $|\mathcal{D}|$ : size of the data set  $\mathcal{D}$  $\gamma$ : a penalty factor

 $d_i$ : no. of free parameters in model  $\Lambda_i$  $|\mathcal{D}|$ : size of the data set  $\mathcal{D}$  $\gamma$ : a penalty factor

### Viewing a K-clustering as a candidate model



An appropriate number of clusters can be determined by  $K^* = \underset{1 \le K \le M}{\operatorname{BIC}(K)}$ .

## **Experimental Results (I)**

### Music data

- 416 tracks from Mandarin pop music CDs
- Sub-set DB-1: 200 tracks
  - 10 male & 10 female singers; 10 different songs/singer
  - Used for the performance evaluation of the singer-based clustering
- Sub-set DB-2: 216 tracks
  - 8 male & 13 female singers; none of the singers appeared in DB-1
  - Used for the training of the vocal and non-vocal models

### Vocal/non-vocal segmentation results

Assessment method

Frame accuracy (in%) =  $\frac{\text{#correctly - classified frames}}{\text{#total frames}} \times 100\%$ 

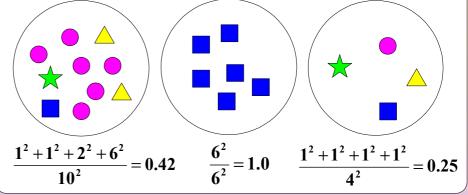
 The performance achieved with the frame-based decision and the segment-based decision were, respectively, 76.8% and 77.6% frame accuracy

### Clustering assessment method

– Cluster purity

$$\rho_k = \sum_{p=1}^p \frac{n_{kp}^2}{n_k^2},$$

*ρ<sub>k</sub>* is the purity of the cluster *k*, *n<sub>k</sub>* the total no. of recordings in the cluster *k*, and *n<sub>kp</sub>* the no. of recordings in the cluster *k* that were performed by singer *p*



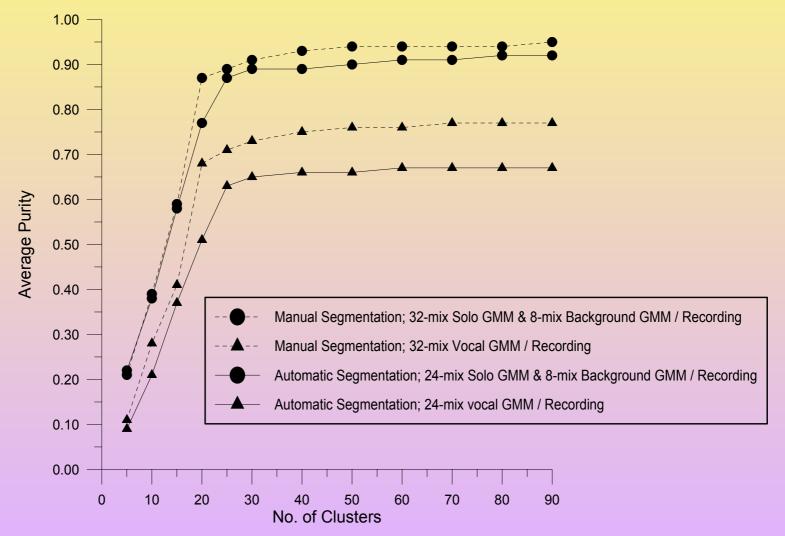
– Average purity

$$\overline{\rho} = \frac{1}{M} \sum_{k=1}^{K} n_k \rho_k,$$

• *M* is the total no. of recordings, and *K* the no. of clusters

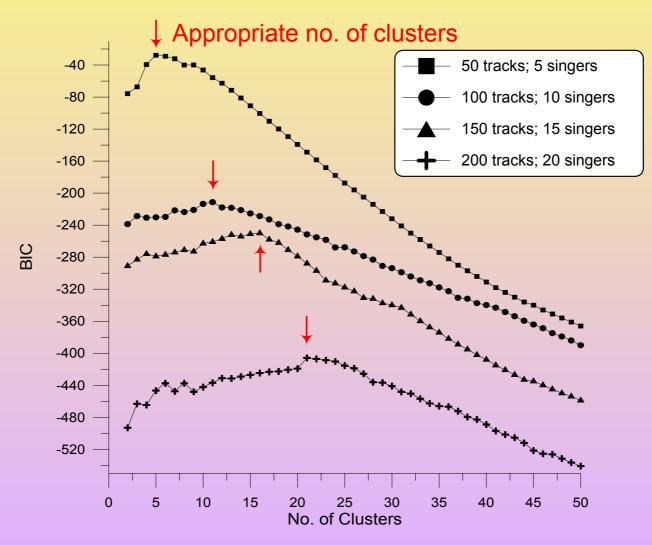
### **Experimental Results (III)**

Result of the clustering for 200 tracks (20 singers × 10 songs)



### **Experimental Results (IV)**

#### Results of automatically determining the no. of clusters



# **Summary**

### We have

- Separated vocal from non-vocal segments of music;
- Isolated singers' vocal characteristics form the background music;
- Clustered music recordings by singer.

#### We will

 Handle a wider variety of music data including duets, trios, chorus, background vocals, or music with multiple simultaneous or nonsimultaneous singers.